

ACM SIGSPATIAL 2020

Topology-Preserving Terrain Simplification

Ulderico Fugacci

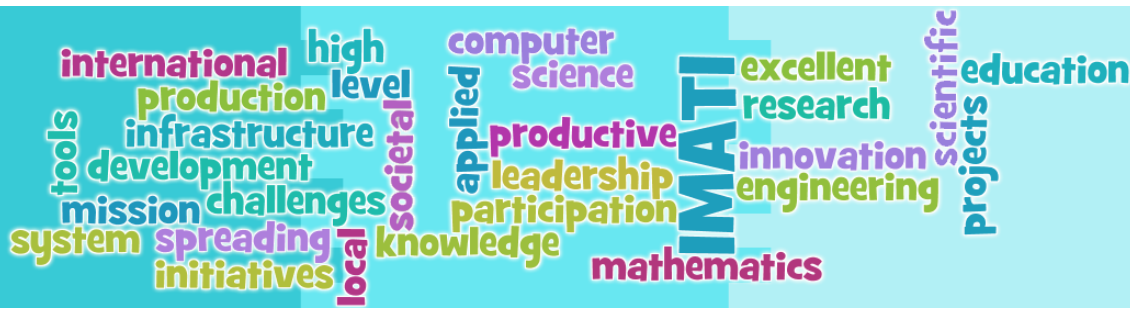
CNR - IMATI

Michael Kerber

TU Graz

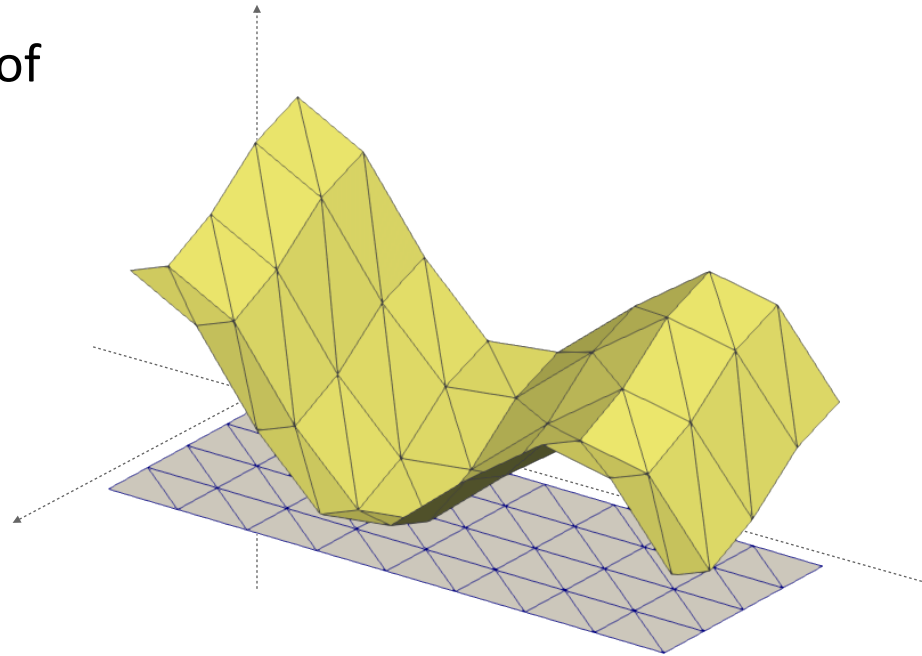
Hugo Manet

ENS Paris



Motivations

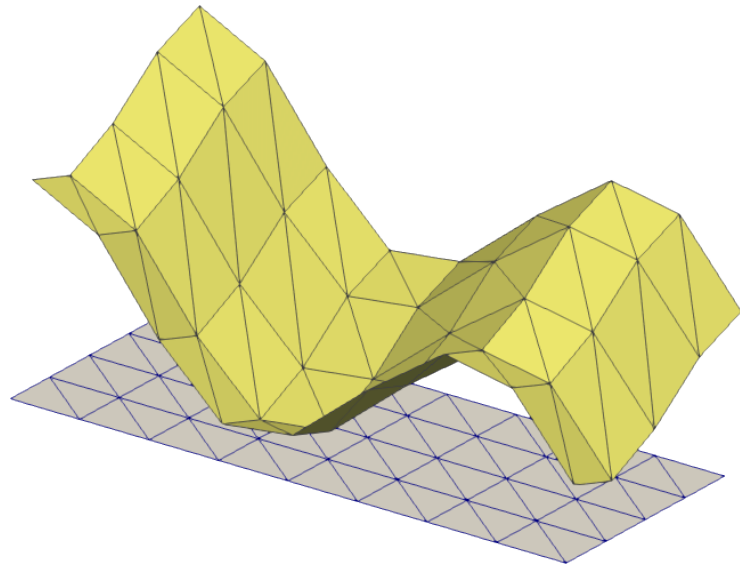
A *terrain* T consists of



- ◆ a **triangulation** of a **compact polygonal region in \mathbb{R}^2** on a set of vertices V (possibly with internal vertices)
- ◆ endowed with an **injective scalar function $t: V \longrightarrow \mathbb{R}$** called **height function**

Motivations

By filtering T through the height function t ,

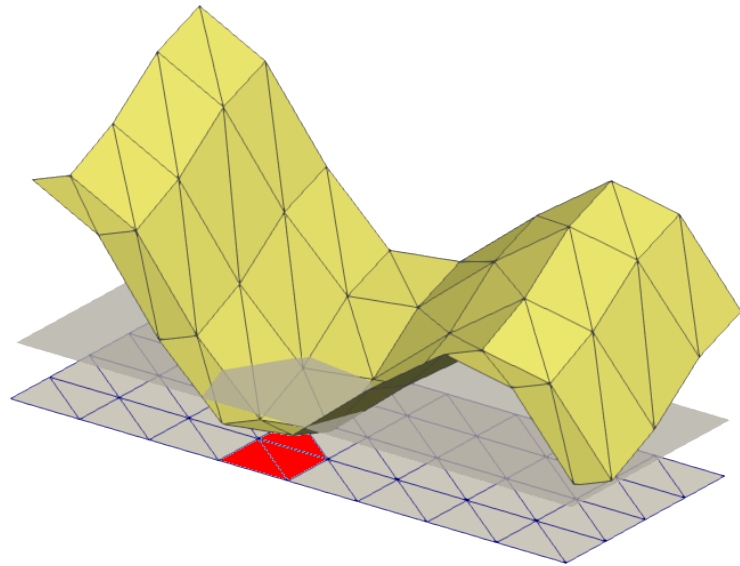


Persistent Homology
enables the study of
terrain morphology

Changes in homology are in correspondence with ***critical points*** of t

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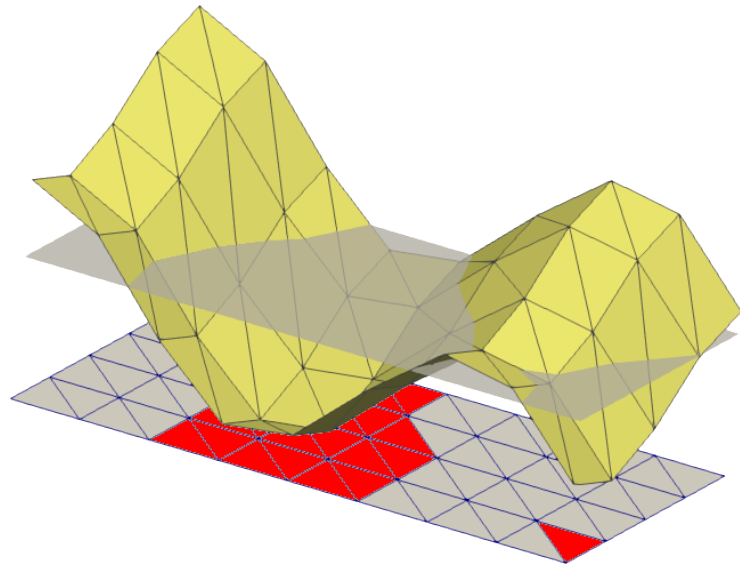


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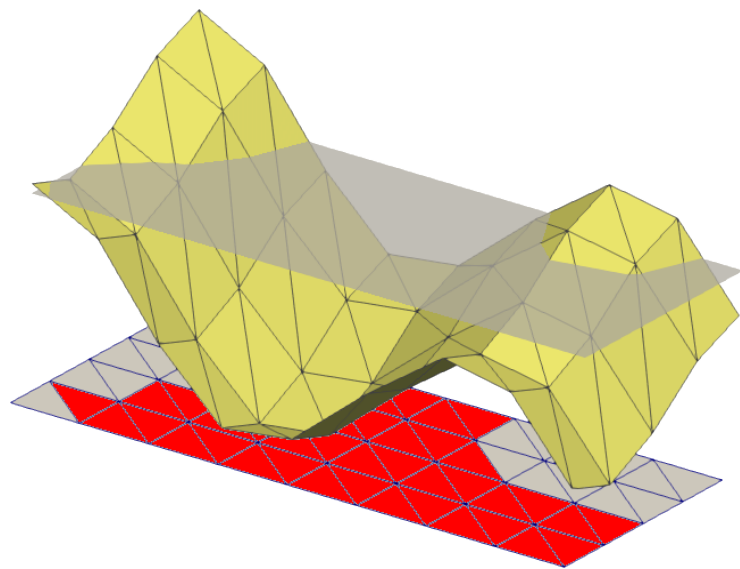


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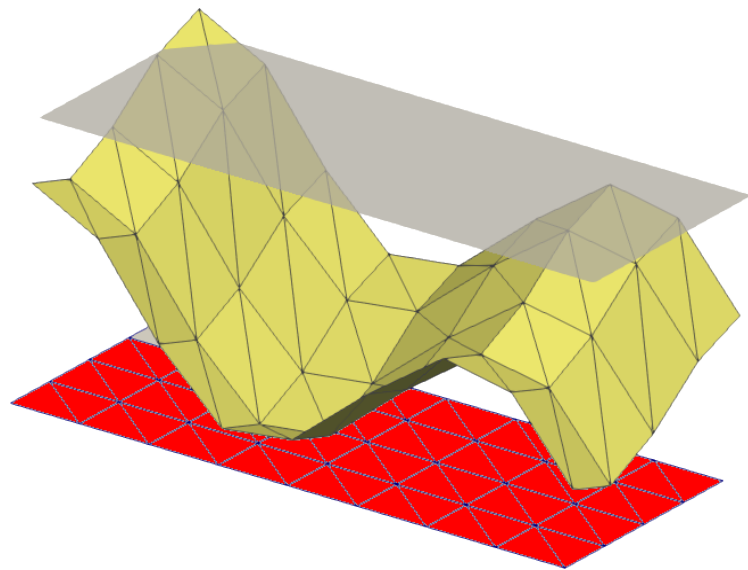


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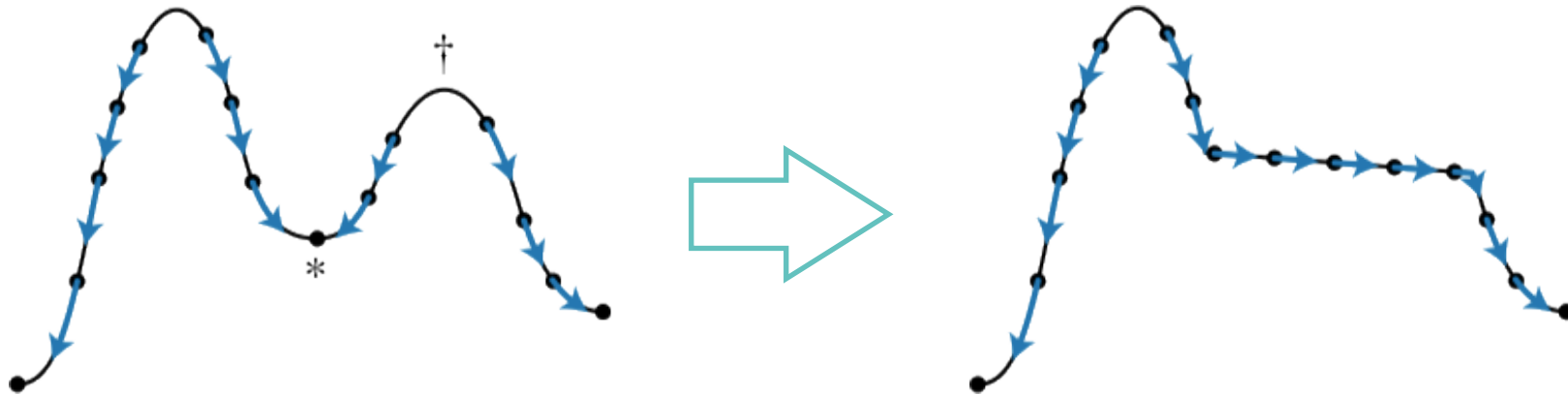


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Changes in homology are in correspondence with ***critical points*** of t

Motivations

Topological terrain simplification consists in the **removal** of



Images from [Bauer et al. 2012]

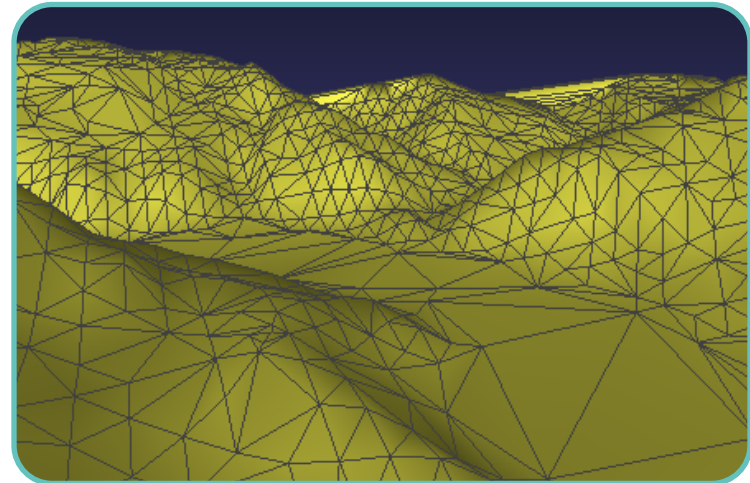
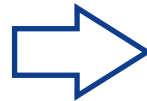
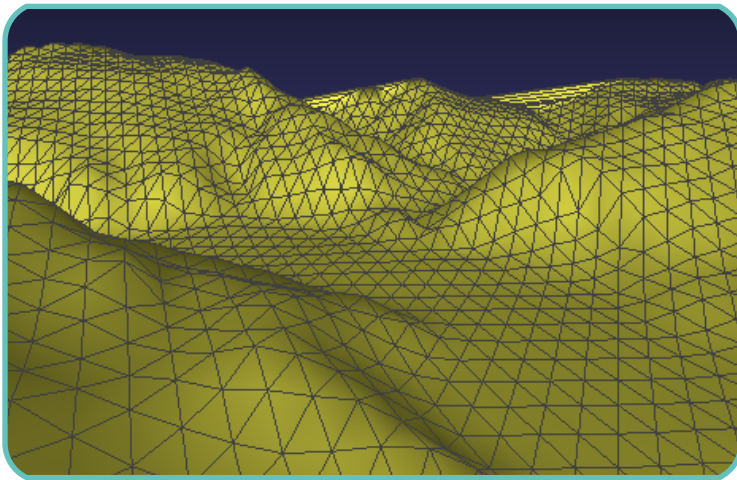
low-persistence pairs of critical points considered as **topological noise**



Output can be affected by **geometrical oversampling**

Motivations

We propose a different approach



- ✦ **Reduce** the *size* of the terrain
- ✦ **Maintain** favorable properties:
 - ✦ *Persistent homology* (i.e. critical points)
 - ✦ *Geometric closeness* to the original surface

Simplification Algorithm

Problem:

Given $\varepsilon > 0$, a base terrain B and a terrain T with $\|B - T\|_\infty \leq \varepsilon$, compute a terrain S with fewer vertices than T , such that $\|B - S\|_\infty \leq \varepsilon$ and S has the *same persistent homology* of T

Algorithm:

Initialize $S \leftarrow T$ and $C \leftarrow \text{Vertices of } T$

while $C \neq \emptyset$,

pick a vertex v in C (uniformly at random) and *remove* it from C

if $\text{link}(v)$ can be *re-triangulated maintaining* the condition on *persistent homology* and L_∞ -*distance* **then**

remove v from S and *re-triangulate* its link by the found triangulation

insert the vertices of $\text{link}(v)$ in C (if not already contained)

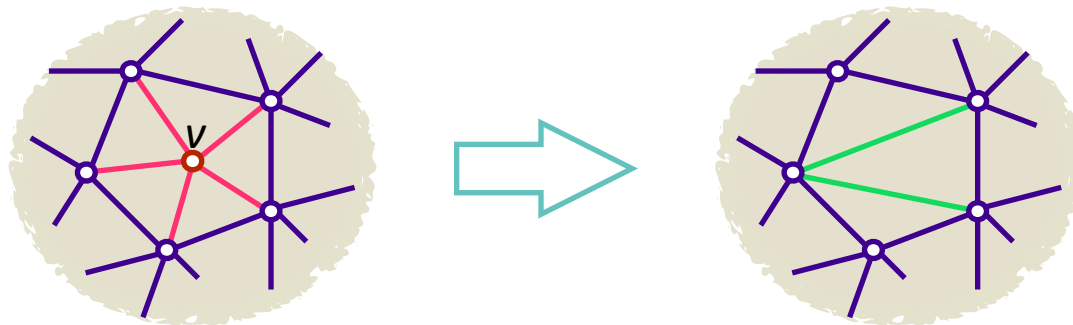
return S

Simplification Algorithm

Theorem:

Given a vertex v of S , a *re-triangulation of its link maintains* the condition on:

- ✦ *L_∞ -distance* if all the *diagonals* and the *triangles* of the re-triangulated link are *L_∞ -aware*
- ✦ *persistent homology* iff v is *not a critical point* and all the *diagonals* of the re-triangulated link are *persistence-aware*



A vertex satisfying the above conditions is called *removable*

Simplification Algorithm

L_∞ -Awareness:

Let u, v, w be vertices of S ,

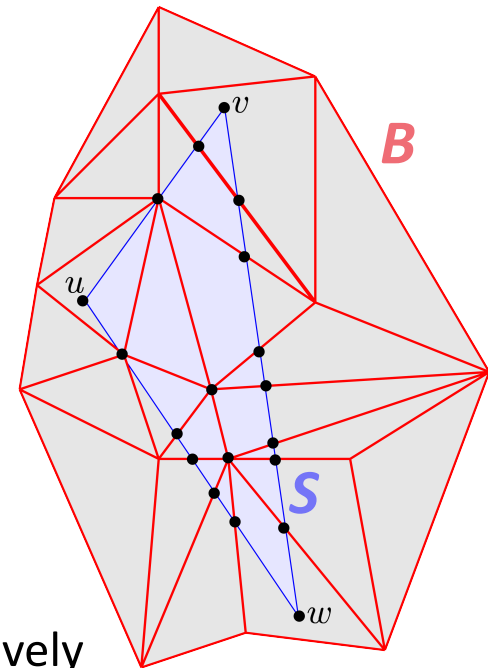
- ◆ uv is called L_∞ -aware if for any point $x = \lambda u + (1-\lambda)v$ of uv ,

$$|(\lambda s(u) + (1-\lambda)s(v)) - b(x)| \leq \varepsilon$$

- ◆ uvw is called L_∞ -aware if for any point $x = \lambda u + \mu v + (1-\lambda-\mu)w$ of uvw ,

$$|(\lambda s(u) + \mu s(v) + (1-\lambda-\mu)s(w)) - b(x)| \leq \varepsilon$$

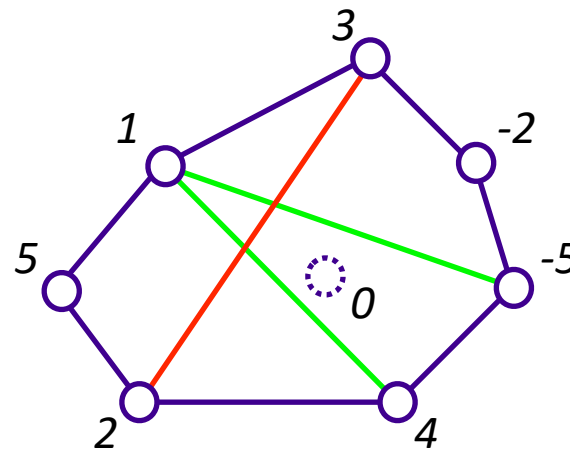
where s and b denote the height functions of S and B , respectively



Simplification Algorithm

Persistence-Awareness:

Let v be a vertex of S with two adjacent vertices u, w such that $s(u) < s(w)$, uw is called *persistence-aware* if one of the following conditions holds:

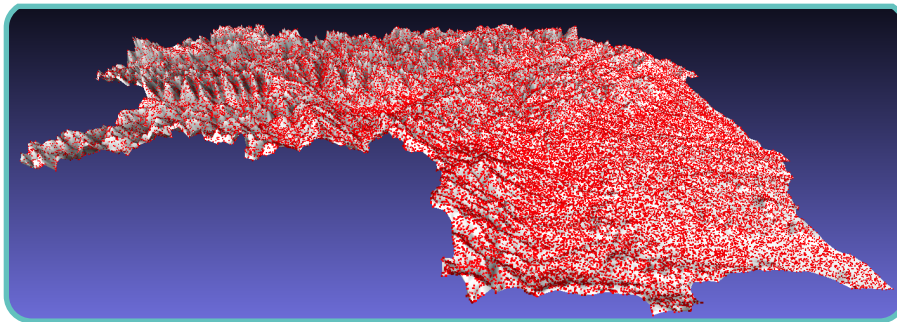


- ◆ $s(u) < s(v) < s(w)$
- ◆ $s(w) < s(v)$ and there is a path on $link(v)$ from u to w with *maximal height* $s(w)$
- ◆ $s(v) < s(u)$ and there is a path on $link(v)$ from u to w with *minimal height* $s(u)$

Implementation & Experiments

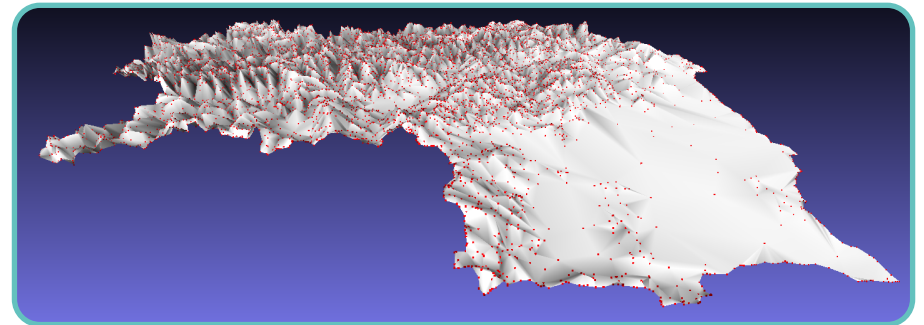
Based on the proposed simplification, an algorithm has been *implemented in C++* and it is available in a *public repository* (https://bitbucket.org/mkerber/terrain_simplification)

Given an *input terrain B* and some $\epsilon > 0$, the algorithm returns a *terrain S* that is ϵ -close to B in L_∞ -distance and has the *smallest number of critical points possible*



Input

Output

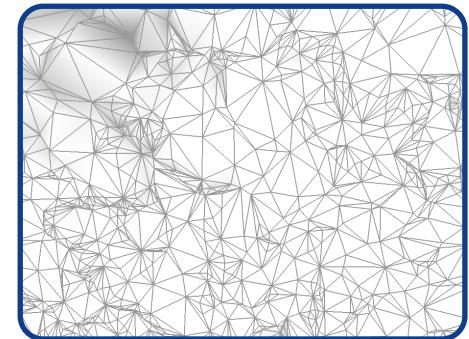
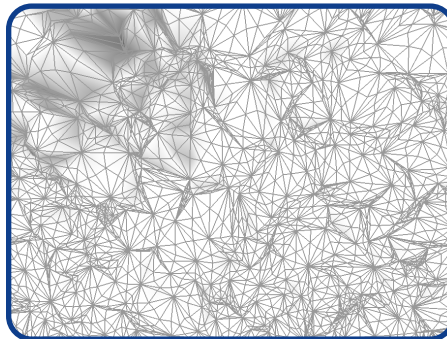
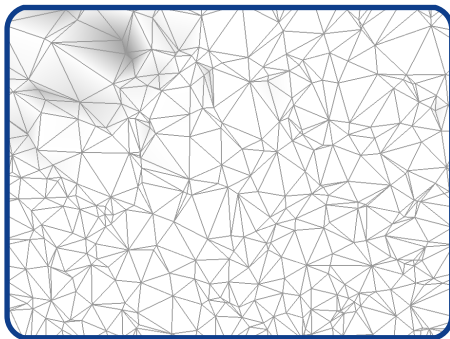


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- ◆ Apply an improved version of the *topological simplification* of [Bauer et al. 2012] on (B, ϵ) to get a terrain T with the specified properties

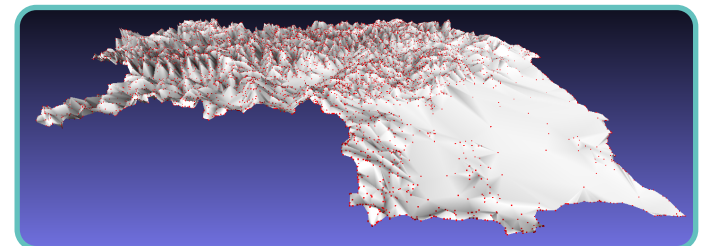
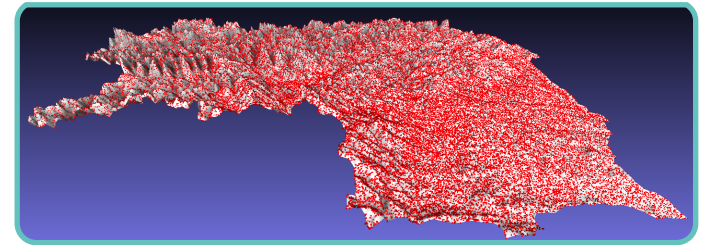


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Given an *input terrain B* and some $\varepsilon > 0$, the algorithm returns a *terrain S* that is *ε -close to B in L_∞ -distance* and has the *smallest number of critical points possible*

- ◆ Apply an improved version of the *topological simplification* of [Bauer et al. 2012] on (B, ε) to get a terrain T with the specified properties
- ◆ Apply our *reduction strategy* on (B, T, ε) to get a smaller terrain S with the same properties

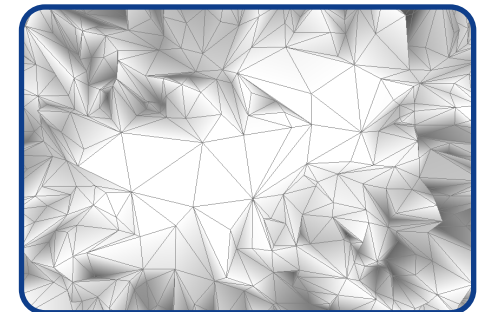
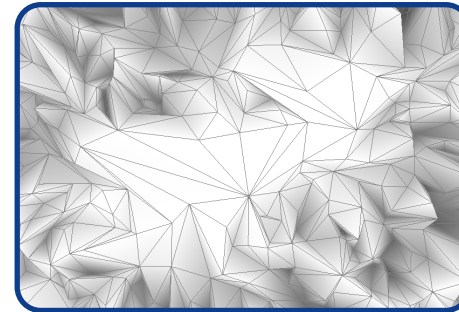


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- ◆ Apply a *mesh improvement* algorithm on (B, S, ε)



Implementation & Experiments

Benchmark Results for Styria Dataset:

I	S	C	O	T
10K	17K	407	4100.6 (± 9.6)	8.90 (± 0.18)
20K	33K	543	6114.2 (± 49.2)	19.96 (± 0.37)
40K	64K	547	8654.2 (± 27.2)	38.96 (± 0.36)
80K	124K	597	11223.2 (± 74.8)	81.19 (± 1.79)
160K	239K	611	13160.2 (± 65.8)	168.54 (± 3.74)
320K	455K	637	15019.0 (± 61.0)	342.40 (± 6.12)

I: size of the input (*number of vertices*)

S: size of the output of the topological simplification algorithm (*number of vertices*)

C: critical points of the output of the topological simplification algorithm

O: size of the final output (*number of vertices*)

T: running time (*in seconds*)

Conclusions

In Summary:

*Based on necessary and sufficient criteria for elementary operations in a terrain to preserve the persistent homology,
we have developed a method to reduce the total size of a topologically simplified terrain
overcoming a major drawback of previous simplification methods
without giving up on its guarantees*

Future Developments:

- ◆ *Investigate how far our output is from an optimal solution*
- ◆ *Extend our implementation to piecewise-linear functions on triangulated surfaces*
- ◆ *Find other interesting application domains*

Thank you

Ulderico Fugacci

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